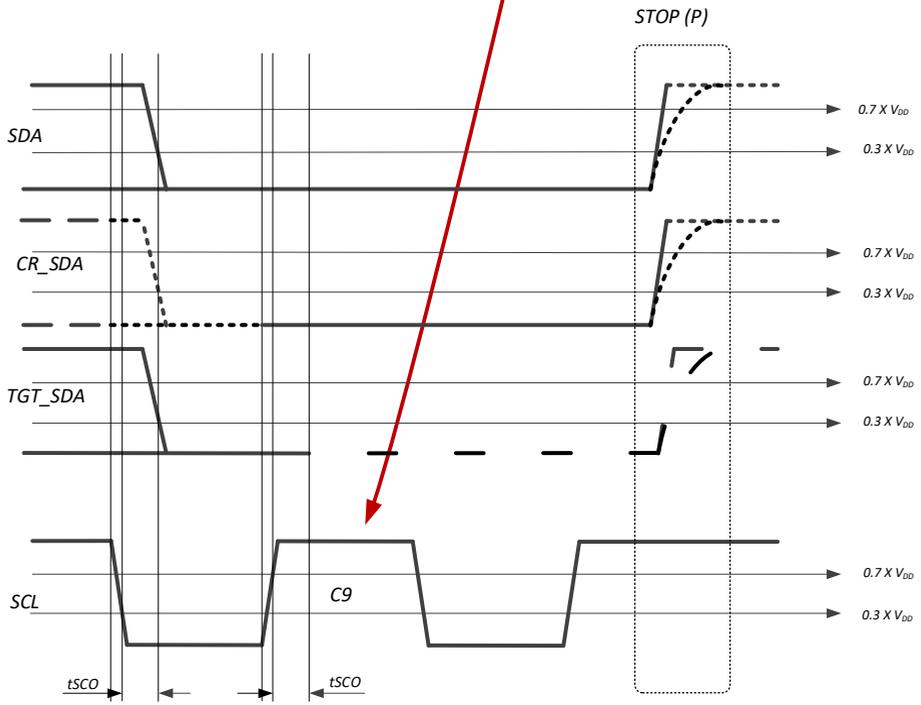


= High Speed Active Push-Pull Drive



Target terminates the Read transfer by pulling SDA Low in 9<sup>th</sup> bit and allowing Controller Device to generate either STOP or RESTART

= Active Drive by Controller or Target     
 = High-Z by Controller  
 = Open-Drain class Pull-Up by Controller     
 = High-Z by Target