MDC or $PGxDC(A) = (PGxPER + 16) \bullet Duty\ Cycle$

Where:
Duty Cycle is % between 0 and 100

$$MPHASE\ or\ PGxPHASE = 16 \bullet F_{PWM} \bullet Phase$$

$PGxTRIGy = 16 \bullet F_{PWM} \bullet Trigger\ Offset$
($y = A,\ B\ or\ C$)

$PGxDTy = 16 \bullet F_{PWM} \bullet Dead\ Time$
($y = H\ or\ L$)

Where:
Phase, *Trigger Offset* and *Dead Time* are specified
in time units (ms, µs or ns)