$MDC \ or \ PGxDC(A) = (PGxPER + 16) \bullet \ Duty \ Cycle$ Where:

Duty Cycle is % between 0 and 100

MPHASE or PGxPHASE = 16 • FPGx clk • Phase

 $PGxTRIGy = 16 \cdot FPGx_clk \cdot Trigger Offset$ (v = A, B or C)

 $PGxDTy = 16 \bullet FPGx_clk \bullet Dead\ Time$ (y = H or L)

Where: Phase, Trigger Offset and Dead Time are specified in time units (ms, µs or ns)